

# Robots and Jobs: Evidence from US Labor Markets

Daron Acemoglu and Pascual Restrepo  
Presentation: Vinzenz Ziesemer

European University Institute

October 2017

# Outline

This paper: Acemoglu and Restrepo (2017)

- ▶ Do robots increase or reduce employment and wages?
- ▶ Model with two main assumptions:
  - Labor and robots are perfect substitutes
  - Local labor markets exist in autarky
- ▶ In that case, (IV) regressions are enough
- ▶ Relax the second assumption: account for trade
  - Now need to calibrate some model parameters
- ▶ Conclusion: robots reduce both employment and wages

From different authors (for a different country):

- ▶ Dauth, Findeisen, Südekum, and Woessner (2017):  
German Robots - The Impact of Industrial Robots on Workers

From the same authors (with the same framework):

- ▶ Acemoglu and Restrepo (2016):  
The Race Between Machine and Man: Implications of  
Technology for Growth, Factor Shares and Employment

# Data and definitions

- ▶ **What** are robots?
  - International Federation of Robotics (IFR): “An automatically controlled, reprogrammable, and multipurpose [machine]”
  - Anything dedicated (suited for only one application) is also excluded (e.g. warehouse storage and retrieval)
- ▶ **Where** are robots (such defined)?
  - Automotive (39%), electronics (19%), metal products (9%), plastic and chemical industry (9%)
  - Place and time: see hereafter
- ▶ **Data** on robots
  - IFR started collecting numbers for Western European economies in 1993 (Denmark, Finland, France, Germany, Italy, Norway, Spain, Sweden, UK)
  - Same for United States in 2004
  - These data are *at industry level*
  - Combine with employment numbers to calculate:  
**robots per worker**

## Empirics: the ascent of robots

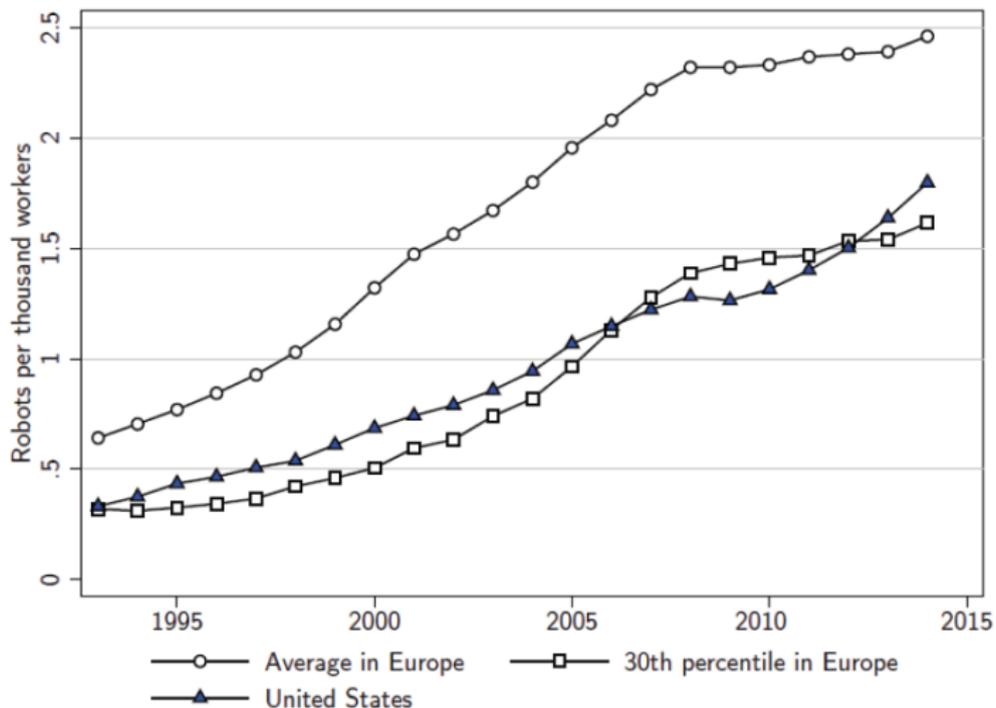
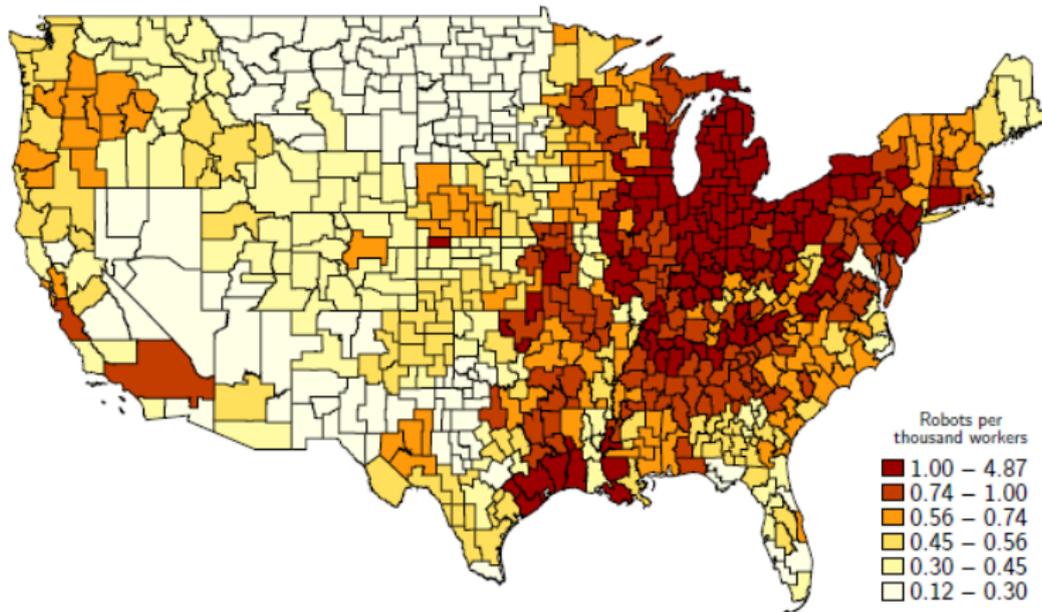


FIGURE 1: INDUSTRIAL ROBOTS IN THE UNITED STATES AND EUROPE.

Note: Industrial robots per thousand workers in the United States and Europe. Data from the International Federation of Robotics (IFR).

# Empirics: geographic variation

## A. Exogenous exposure to robots from 1993 to 2007



- ▶ Constructed data: industry level data on robots, commuting zone level data on industry shares
- ▶ 'Exogenous' means instrumented by European robot use data

## Autarky Model: consumption

- ▶ Commuting zones  $c$ , industries  $i$
- ▶ Preferences of a commuting zone

$$Y_c = \left( \sum_{i \in \mathcal{I}} \alpha_i Y_{ci}^{\frac{\sigma}{\sigma-1}} \right)^{\frac{\sigma-1}{\sigma}} \quad (1)$$

- ▶  $\sigma$  elasticity of substitution across goods (industries), shares  $\sum_{i \in \mathcal{I}} \alpha_i = 1$
- ▶ Autarky: production  $X_{ci}$  and

$$Y_{ci} = X_{ci} \quad (2)$$

## Autarky Model: production

- ▶ Production of each good requires tasks  $x_{ci}(s)$  indexed  $s \in [0, S]$

$$X_{ci} = A_{ci} \min_{s \in [0, S]} \{x_{ci}(s)\} \quad (3)$$

- ▶ NB: There are no choices here, this is a Leontief!
- ▶ Each task also has a production function, form depends on technology frontier  $M_i \in [0, S]$ :

$$x_{ci}(s) = \begin{cases} \gamma l_{ci}(s) + r_{ci}(s) & \text{if } s < M_i \\ \gamma l_{ci}(s) & \text{if } s \geq M_i \end{cases} \quad (4)$$

- ▶  $r_{ci}(s)$  are robots, perfect substitutes for labor
- ▶  $\gamma$  is the relative productivity of labor

## Autarky Model: labor and robot supply

- ▶ Labor  $L_c$  and robot supply  $R_c$  depend on wages and robot costs ( $W_c$  and  $Q_c$ ) in some reduced form:

$$W_c = \mathcal{W}_c Y_c L_c^\epsilon \quad (5)$$

$$Q_c = \mathcal{Q}_c \left( \frac{R_c}{Y_c} \right)^\eta \quad (6)$$

- ▶  $1/\epsilon$  is Frisch elasticity of labor supply
- ▶  $1/\eta$  elasticity of robot supply, cost is convex in robots (e.g. due to limited supply of local 'integrators')
- ▶ Firms assumed competitive, prices  $P_{X_{ci}}$  equal unit cost
- ▶ Equilibrium: firms maximize profits, both markets clear
- ▶ Key assumption: cost savings gain  $\pi_c = 1 - \frac{Q_c \gamma}{W_c} > 0$  in all tasks, i.e. production is on technology frontier  $M_i$

## Autarky Model: results

- ▶ Partial equilibrium effect of automation:

$$d \ln L_c^d = - \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dM_i}{1 - M_i} - \sigma \sum_{i \in \mathcal{I}} \ell_{ci} d \ln P_{Xci} + d \ln Y_c \quad (7)$$

- ▶ where  $\ell_{ci} = \frac{l_{ci}}{\sum_{i \in \mathcal{I}} l_{ci}}$
- ▶ = *displacement effect* (workers replaced) – *price-productivity effect* (industry expands) + *scale-productivity effect* (overall demand rises)
- ▶ General equilibrium version (not entirely in fundamentals!):

$$d \ln L_c = - \frac{1 + \eta}{1 + \epsilon} \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dM_i}{1 - M_i} + \frac{1 + \eta}{1 + \epsilon} \pi_c \sum_{i \in \mathcal{I}} \ell_{ci} \frac{s_{icL}}{s_{cL}} \frac{dM_i}{1 - M_i} \quad (8)$$

- ▶ where  $s_{icL}$  is labor share of income
- ▶ = *displacement effect* (workers replaced) + *productivity effect*
- ▶ Similar for wages

## Autarky Model: at $M \approx 0$

- ▶ Restating:

$$d \ln L_c = -\frac{1+\eta}{1+\epsilon} \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dM_i}{1-M_i} + \frac{1+\eta}{1+\epsilon} \pi_c \sum_{i \in \mathcal{I}} \ell_{ci} \frac{s_{icL}}{s_{cL}} \frac{dM_i}{1-M_i} \quad (9)$$

- ▶ At  $M \approx 0$ :

$$\sum_{i \in \mathcal{I}} \ell_{ci} \frac{s_{icL}}{s_{cL}} \frac{dM_i}{1-M_i} \approx \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dM_i}{1-M_i} \approx \frac{1}{\gamma} \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dR_i}{L_i} \quad (10)$$

- ▶ Similar for wages
- ▶ Call the last term **exposure to robots**
- ▶ Empirically ( $M \approx 0$  in 1990) we then have that:

$$d \ln L_c = \beta_c^L \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dR_i}{L_i} + \epsilon_c^L \quad (11)$$

## Channels (1/3)

What do increases in automation do to employment?

- ▶ Keynes famously predicted 'technological unemployment'
- ▶ Some preliminary remarks:
  - The model does not formally separate the intensive and extensive margins of labor supply - only relevant for overall labor supply, which is positively related to wages by assumption
  - The authors seem to think of this as 'extensive margin only'
  - SBTC: Any technological progress increases all wages
    - ▶ Simply a feature of (one good, one task, closed economy) CES production in competitive markets
    - ▶ No longer the case here
- ▶ There are many adjustment channel

## Channels (2/3)

- ▶ Adjustment channels:
  1. Technology may be prohibitively expensive
    - ▶ Here: focus on robots that actually go into use
  2. A small drop in wages may make labor competitive again
    - ▶ Here: excluded, remain at frontier by assumption
  3. Technology may not be a perfect substitute, mitigates impact
    - ▶ Here: excluded, perfect substitute
  4. Technology has different complementarity with other tasks
    - ▶ Here: excluded
  5. Other tasks could absorb labor (wages would still fall)
    - ▶ Here: excluded, Leontief
  6. Other goods could absorb labor (wages would still fall)
    - ▶ Here: included
  7. Technology improves competitiveness in trade
    - ▶ Here: not yet included (but will be)
  8. Labor could migrate (wages would still fall?)
    - ▶ Here: excluded
  9. Income effect from increased productivity
    - ▶ Here: included

## Channels (3/3)

What do increases in automation do to labor?

- ▶ Abstract from cost competition with labor (1,2) as would not see this in data
- ▶ Several missing channels (3-5, 8; 6 is included) would still see falling wages, but mitigate the effect
  - Of these, labor mobility (8) seems particularly pertinent
- ▶ Trade competitiveness and income effects from productivity (7 and 9) can turn the effect of robots around
  - Former (7) is included later, latter (9) is included

## Empirical Approach

- ▶ Important to note: without belief in the theory, we could still investigate the effect of local *exposure to robots* on local employment and wages
- ▶ But: endogeneity issues plague the *exposure to robots* measure
  - Any number of things could have occurred in these sectors concurrently, influencing both employment and robots
- ▶ Authors deal with this in two ways
  - Use data on European robot-per-worker growth as an instrument
  - A battery of robustness checks for: broad industry composition, demographics, exposure to imports from China, from Mexico, capital stock growth, IT capital growth, decline in routine jobs, off-shoring of intermediate inputs, past trends in employment and wages
- ▶ Result: one more robot per thousand workers reduces aggregate employment to population by 0.37 percentage points (6 workers) and average wages by 0.73 percent
  - Results are robust for many different specifications

## Trade Model

- ▶ Trade at no cost, prices  $X_{cdi}$ ; market clearing now:

$$X_{ci} = \sum_{d \in \mathcal{C}} X_{cdi} \quad (12)$$

- ▶ Treat different origins as varieties (for internal solutions):

$$Y_{ci} = \left( \sum_{s \in \mathcal{C}} \theta_{si} X_{sci}^{\frac{\lambda-1}{\lambda}} \right)^{\frac{\lambda}{\lambda-1}} \quad (13)$$

- ▶ Assume  $\lambda > \sigma$ ,  $\sigma \geq 1$
- ▶ Equilibrium now further requires:

$$Y_c = \sum_{i \in \mathcal{I}} X_{ci} P_{X_{ci}} \quad (14)$$

## Trade Model: results

- ▶ Partial equilibrium:

$$\begin{aligned}d \ln L_c^d = & - \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dM_i}{1 - M_i} - \lambda \sum_{i \in \mathcal{I}} \ell_{ci} d \ln P_{Xci} \\ & + (\lambda - \sigma) \sum_{i \in \mathcal{I}} \ell_{ci} d \ln P_{Yi} + d \ln Y_c\end{aligned}\quad (15)$$

- ▶ Industry advantage became greater than before (second term,  $\lambda > \sigma$ ), but this is partially undone because robots also arrive elsewhere (third term)
- ▶ General equilibrium version is very involved, but depends on similar fundamentals as before

## Trade Model: aggregation

- ▶ We want to have aggregate employment effects
- ▶ Under the assumption that  $\pi_c = \pi$ , and that  $M_i = M \approx 0$ , we have the following aggregate employment effects:

$$\frac{1 + \eta}{1 + \epsilon} (\pi - 1) \frac{1}{\gamma} \mathbb{E}_c \sum_{i \in \mathcal{I}} \ell_{ci} \frac{dR_i}{L_i} \quad (16)$$

- ▶ Note that we are now taking averages over commuting zones
- ▶ No variation left to regress

## Trade Model: calibrated parameters

- ▶ To calculate quantities, we now require estimates of fundamental parameters
- ▶ Regression estimates can still be connected to fundamental parameters
- ▶ Setting some of these with standard values from the literature, the remainder can be backed out
- ▶  $\pi$  turns out to be the key parameter to which the results are sensitive
  - These are the cost savings from introducing robots
  - Calibrated on the basis of business consulting case studies
- ▶ Result: effect on employment 10% lower than local effect, effect on wages 30% lower; 0.13% increase in GDP from an extra robot per thousand workers

# Conclusion

- ▶ Focuses on observable and new substitute for labor
- ▶ Employment  $\neq$  welfare
- ▶ Theory highlights some of the relevant channels (but not all)
- ▶ Empirical strategy may identify local effects well
- ▶ Aggregated measurements may be sensitive to assumptions
- ▶ And to missing channels:
  - Gathmann, Helm, and Schönberg (2016) find that labor mobility shields German workers under 50 from employment losses due to mass layoffs
- ▶ Overall, the impression remains that this empirical question is hard to answer

## Dauth, Findeisen, Südekum, and Woessner (2017): German Robots

- ▶ Do the (exact) same thing to estimate local effects in Germany, which is way more exposed to robots
- ▶ Find that local effects are zero - nothing to say on aggregates
  - Composition: two jobs disappear in manufacturing, get created in services
  - Wages fall overall, size is sensitive to controls but about half as large as the local effects in Acemoglu and Restrepo (2017)
  - Distribution: high skills gain, others loose
- ▶ Also look at firm aggregates at regional level, find robots cause(!?) declining labor share due to increased profits
- ▶ Have micro survey data on companies
  - Find that robot exposed have a higher probability of keeping their job
  - Smaller flow of entrants to these jobs
  - They attribute the difference to the US to unions' power, who care for full employment
- ▶ Let's look at automotive

# Most (and many) robots arrive in automotive

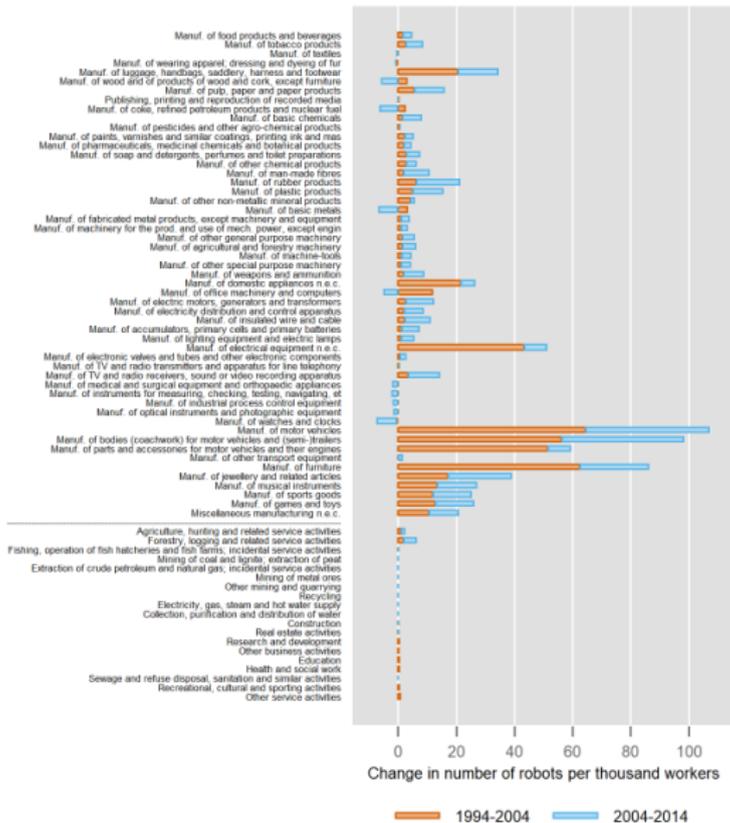


Figure 2: Industry-level distribution of robots

## Automotive grows explosively due to emerging markets demand

- ▶ 'Installed' cars (meaning after some go out of circulation) grows at 4% per annum globally due to emerging markets demand
- ▶ Two-thirds of German automotive sales are for export
- ▶ High skilled workers for global production are in Germany: where the robots arrive is where the money is made (spillovers!)
- ▶ This is a global trend (just like, and concurrent with, robots) that the IV (other countries at industry level) cannot deal with
- ▶ Could this bias results upwards?
- ▶ Excluding the top two automobile locations, one robot replaces almost one worker (but not statistically significant)

## Why would local effects be smaller in Germany?

- ▶ As noted, issues with global demand for certain products
- ▶ Also, think of robot arrival timing as a cost issue, instead of technology/innovation
  - The productivity effect is always zero in this case
  - Robots arrive sooner when they are cheaper, when labor is more expensive, when complementary skills are abundant (e.g. installation)
  - The more productive a robot (at given price) is when this condition is met, the more labor it (i.e. one robot) can replace
  - How much labor there is to replace depends on earlier productivity choices
- ▶ Could this be a relevant difference between the US and Germany?
- ▶ Distinction between the two ways of thinking about robot arrival may not be innocuous at all (for example when aggregating local effects)
- ▶ Germany and the US cannot be seen in isolation: all the action is in industries where they compete intensely - see Acemoglu and Restrepo (2017)!

# Acemoglu and Restrepo (2016): The Race Between Machine and Man

- ▶ Most advanced version of the task-based model
- ▶ Main differences to this version:
  - Production does not happen at technological frontier  $M_i$  when labor is cheap
  - Not only the technological frontier  $M_i$  can move, but also the set of tasks:
    - ▶ New tasks are the most complex, and can only be performed by labor (until the technology frontier advances there)
- ▶ Introduce trade-off between advancing the set of tasks (using labor), or automating production (using capital)
- ▶ Former happens when labor is cheap and makes labor more expensive, latter vice versa
- ▶ Authors demonstrate some sufficient conditions for balanced growth path (with constant wage growth)
- ▶ Other results: on factor shares, welfare (model of innovation)

## Literature I

- Acemoglu, D. and P. Restrepo (2016). The race between machine and man: Implications of technology for growth, factor shares and employment. Technical report, National Bureau of Economic Research.
- Acemoglu, D. and P. Restrepo (2017). Robots and jobs: Evidence from us labor markets.
- Dauth, W., S. Findeisen, J. Südekum, and N. Woessner (2017). German robots-the impact of industrial robots on workers.
- Gathmann, C., I. Helm, and U. Schönberg (2016). Spillover effects of mass layoffs. Technical report, Working Paper, University College London.